

- R) - Q(R) N

 $\frac{dN}{dt} = f(R)N = (\eta q(R) - u)N$

THEORY-BASED ECOLOGY

A Darwinian approach

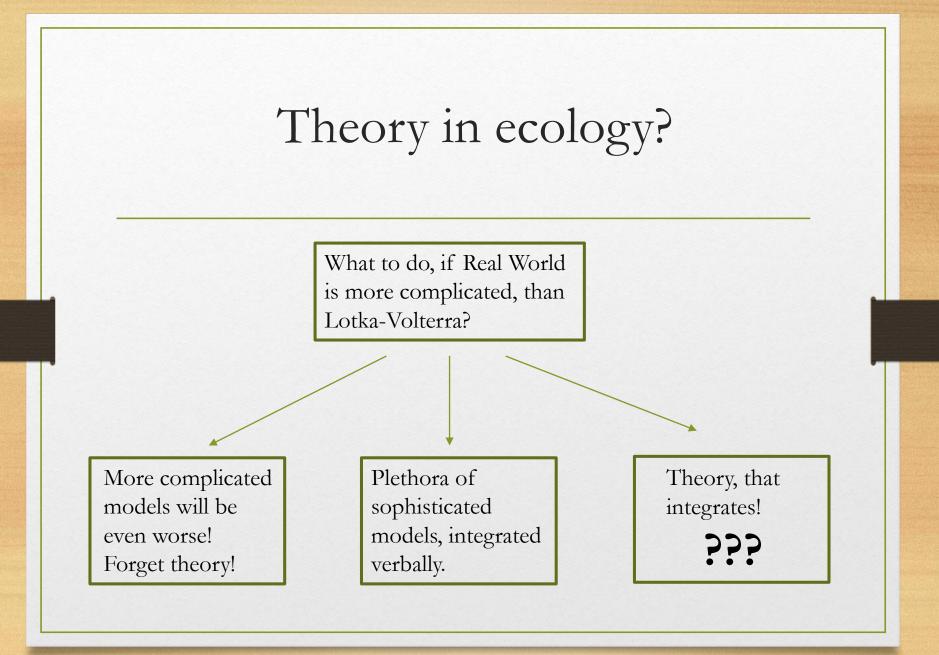
Liz Pásztor, Zoltán Botta-Dukát, Gabriella Magyar, Tamás Czárán, and Géza Meszéna

W = a=== 87

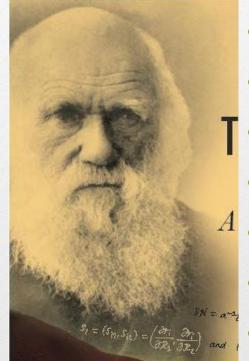
deta = det3 det 7

 $S_{l} = (S_{\gamma_{l}}, S_{\gamma_{l}}) = \left(\frac{\partial r_{i}}{\partial \mathcal{P}_{j}}, \frac{\partial r_{i}}{\partial \mathcal{P}_{j}}\right) \text{ and } l_{j} = \left(\frac{l_{j}}{l_{i}}, \frac{l_{j}}{l_{j}}\right) = \left(\frac{\partial \mathcal{P}_{l}}{\partial \mathcal{P}_{i}}, \frac{\partial \mathcal{P}_{l}}{\partial \mathcal{P}_{j}}\right)$

pgr(w, M, R)

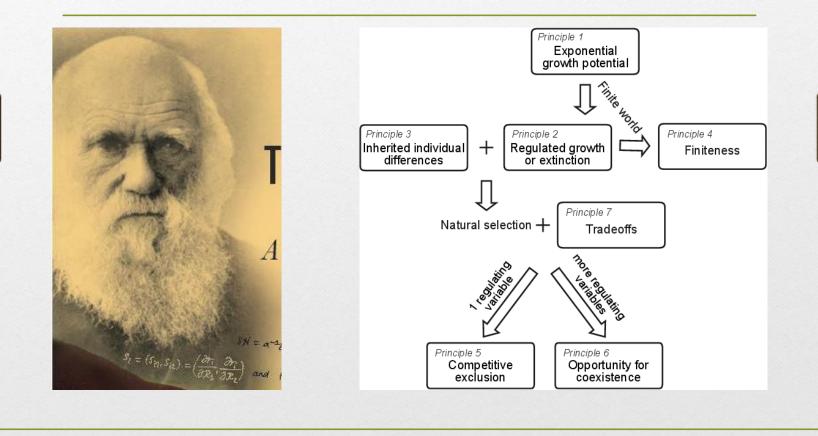


Darwinian principles



- Exponential growth.
- Growth regulation.
- Inherited differences.
- Survival of the fittest.
- Constraints and tradeoffs.
- Robust coexistence.
- Finiteness of populations.

Darwinian principles

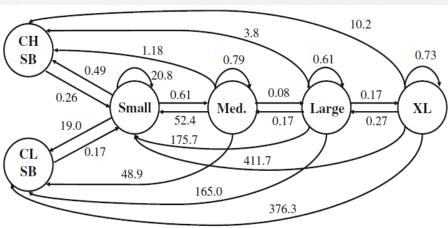


Sources of complexity

- Stochasticity of life histories
- *i*-states and structured populations
- Complexity of interactions between individuals
- Complexity of population dynamics
- Environments changing in space and time
- Complexity of communities
- Linking theory and data

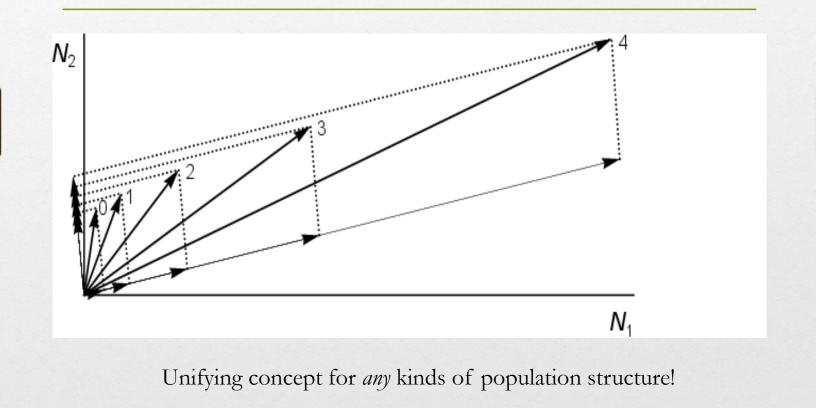
Structured population: an example from the many

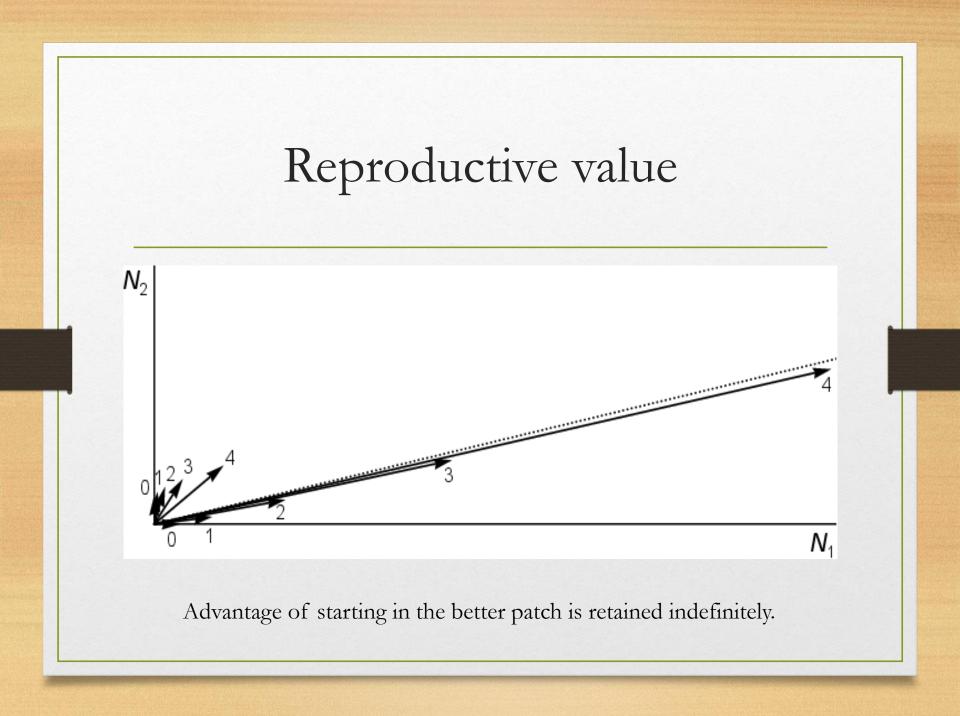




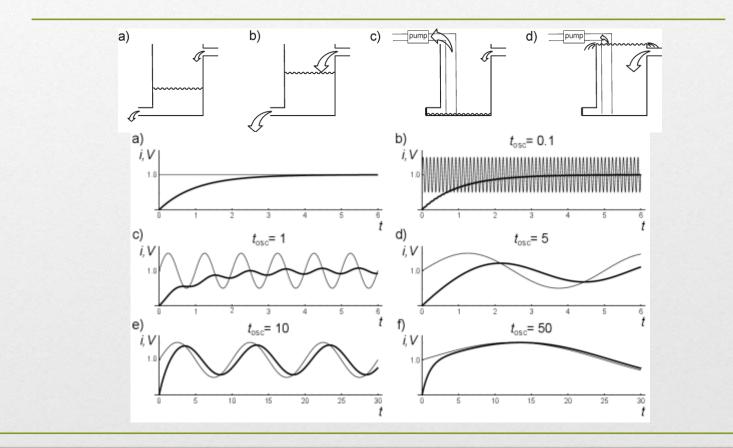
Lespedeza cuneata (Schutzenhofer et al. 2009)

Population structure: Matrix & eigenvector/value

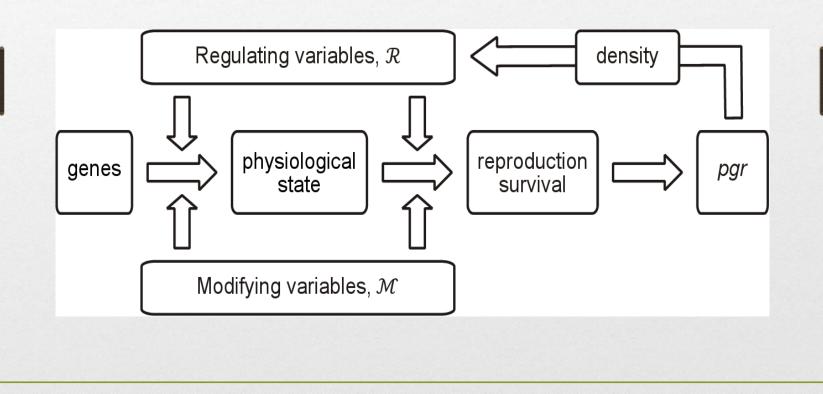


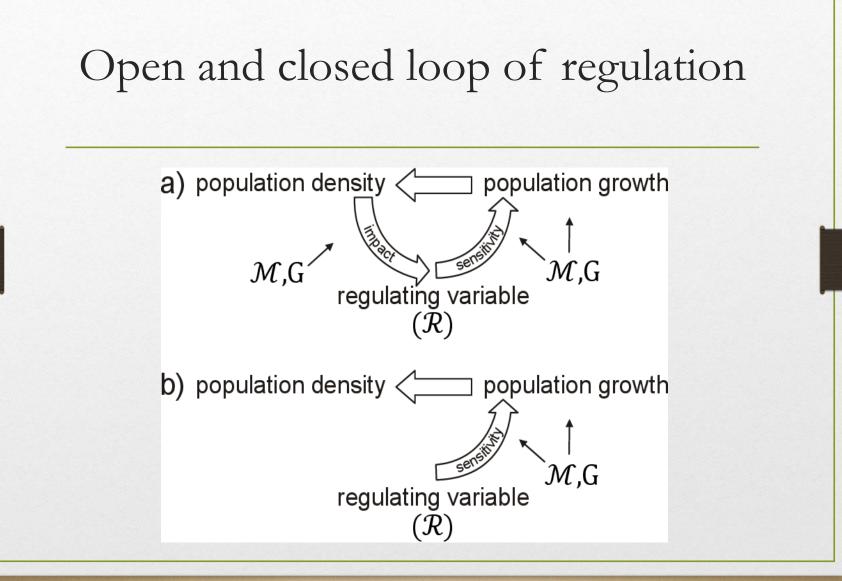


Negative feedback & time-scale separation

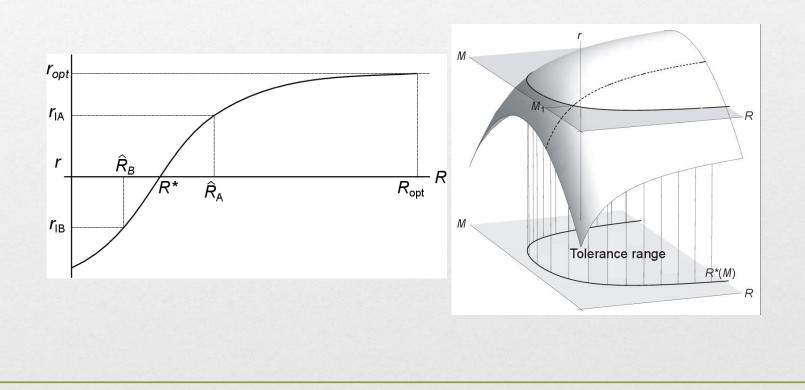


Chain of effects and the environmental feedback

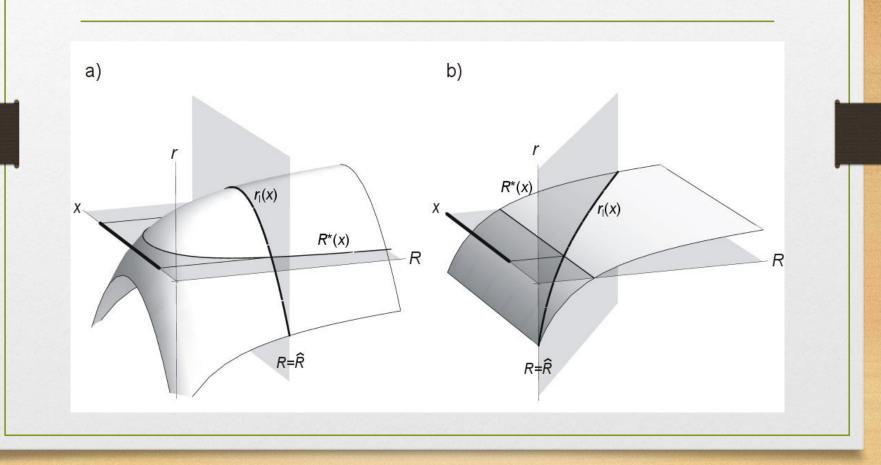








Spatial distribution



Bottom-up control

$$\frac{dR}{dt} = \alpha(\hat{R} - R) - \varrho(R)N$$

$$\frac{dN}{dt} = r(R)N = (\gamma\varrho(R) - u)N$$

$$R = R^*$$

$$R = \bar{R}(N) = \frac{\alpha}{\alpha + \beta N}\hat{R}$$

$$I = \frac{d\bar{R}(N)}{dN} = -\frac{\alpha\beta}{(\alpha + \beta N)^2}\hat{R}$$

$$\bar{r}(N) = \frac{\alpha\beta\gamma}{\alpha + \beta N}\hat{R} - u$$

$$S = \frac{dr(R)}{dR} = \gamma\beta$$

$$a = -\frac{d\bar{r}(N)}{dN} = -S \cdot I = \frac{\alpha\beta^2\gamma}{(\alpha + \beta N)^2}\hat{R}$$

Dynamics.

Holling I, R is fast:

Top-down control

Dynamics:

$$\frac{dR}{dt} = \alpha(\hat{R} - R) - \beta^{N}RN$$

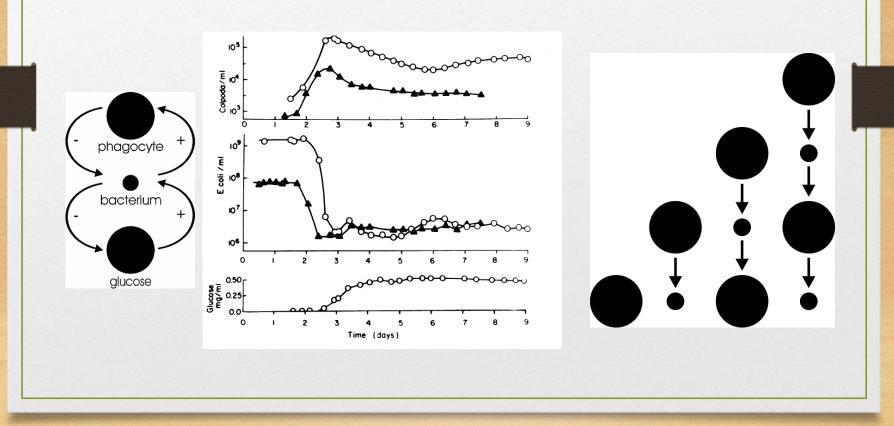
$$\frac{dN}{dt} = (\gamma^{N}\beta^{N}R - u^{N})N - \beta^{P}NP$$

$$\frac{dP}{dt} = (\gamma^{P}\beta^{P}N - u^{P} - bP)P$$

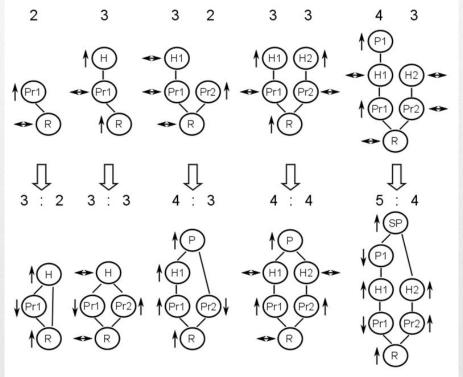
Regulation: $a = -\frac{d\bar{r}}{dN} = -\frac{\partial r}{\partial R}\frac{d\bar{R}}{dN} - \frac{\partial r}{\partial P}\frac{d\bar{P}}{dN} = a^{R} + a^{P}$ $a^{P} = -S^{P} \cdot I^{P} = \frac{\gamma^{P}(\beta^{P})^{2}}{b} \to \infty \qquad \text{when } b \to 0$

Rule of exclusive resource limitation (Fretwell 1977)

Exclusive resource limitation



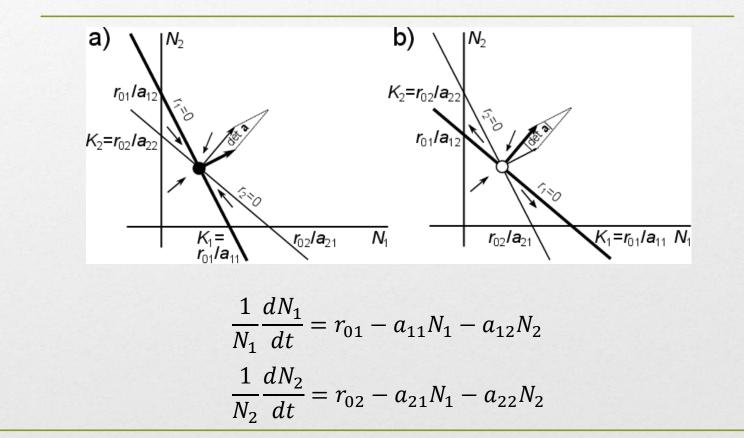
Consequence for trophic networks



How does the network react to an increase of resource input?

(Wallrab, Diehl, de Roos, 2012)

Coexistence in Lotka-Volterra



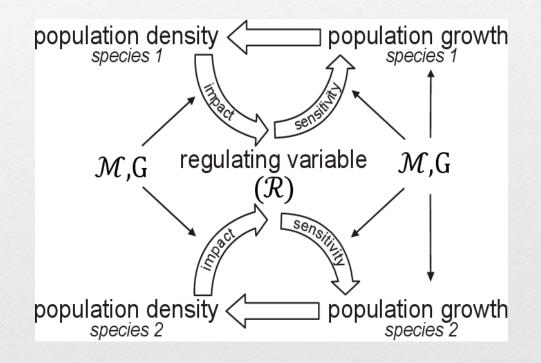
Robustness of coexistence

 $\boldsymbol{r}(\boldsymbol{N}) = \boldsymbol{r}_0 - \boldsymbol{a}\boldsymbol{N} = \boldsymbol{0}$

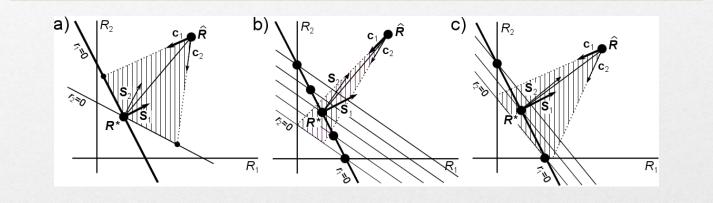
 $N = a^{-1}r_0$

$$\boldsymbol{a}^{-1} = \frac{1}{\det \boldsymbol{a}} \begin{pmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{pmatrix}$$

det *a* small ↓ Coexistence is not robust. Interactions through regulating variables

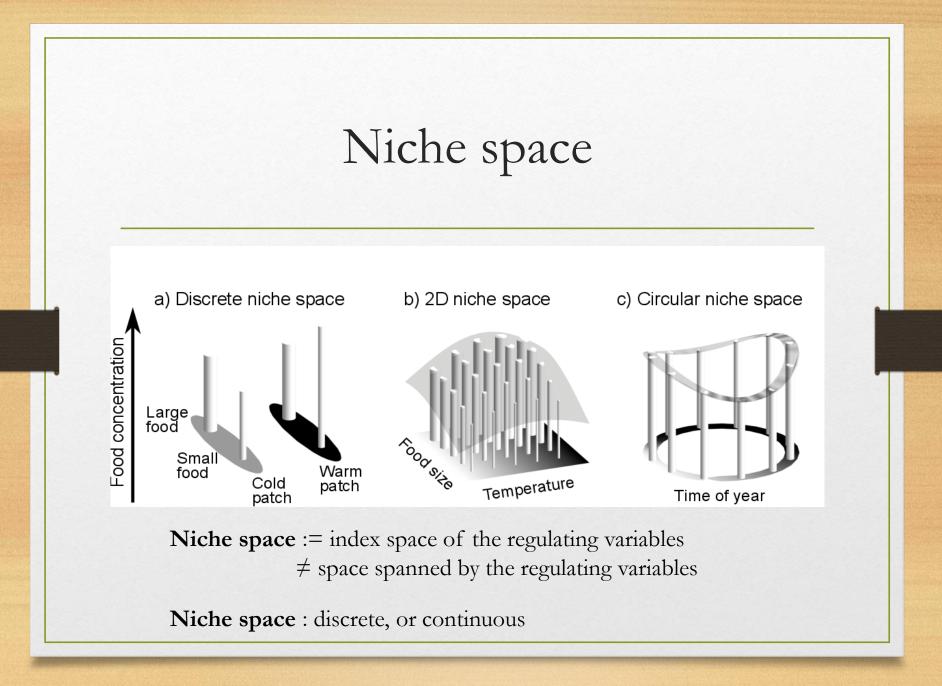


Robustness of coexistence



$$a_{ij} = -\frac{\partial r_i}{\partial N_j} = -\frac{\partial r_i}{\partial \boldsymbol{\mathcal{R}}} \cdot \frac{\partial \boldsymbol{\mathcal{R}}}{\partial N_j} = -\frac{\partial r_i}{\partial \boldsymbol{\mathcal{R}}_1} \cdot \frac{\partial \boldsymbol{\mathcal{R}}_1}{\partial N_j} - \frac{\partial r_i}{\partial \boldsymbol{\mathcal{R}}_2} \cdot \frac{\partial \boldsymbol{\mathcal{R}}_2}{\partial N_j} = -\boldsymbol{S}_i \cdot \boldsymbol{I}_j$$

Robust coexistence: Populations must differ sufficiently in both I and S!



Mathematics of ecology⊂ Mathematics of life

- We suggest an integrated theory of ecology.
- It is tautologic, as any math; not a replacement for understanding your specific system..
- Without such integration, ecology would remain stuck in hopeless debates.
- We tried to keep math as minimalist, as possible in the book.
- Still, the integration would not be possible without deep mathematics.

We thank Hans & *Mats* & the adaptive dynamics people for helping some authors to write many papers and a book on us.

Giant Tortoise community (Galapagos)

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