

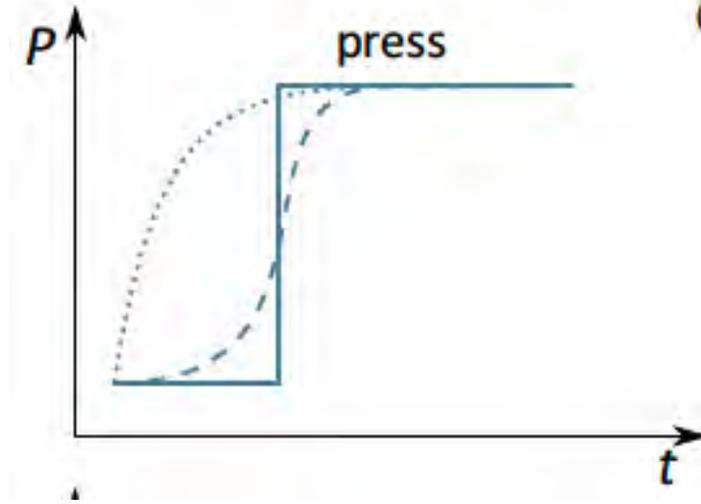
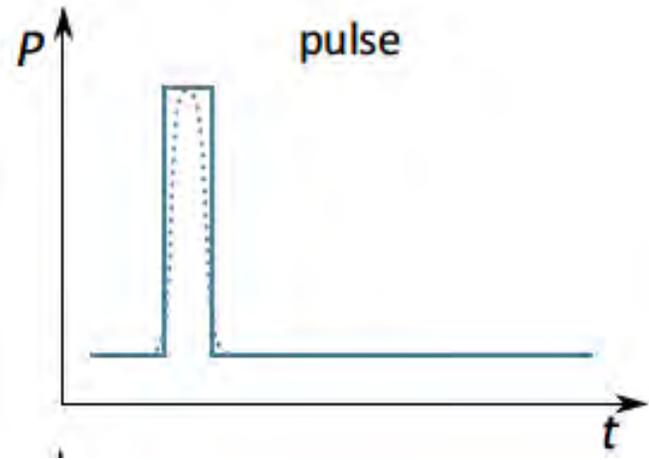
Pulses, Presses, and Nonlinear Response

Shripad Tuljapurkar

Harman Jaggi, Wenyun Zuo, Sam Gascoigne, Maja Kalin, Roberto Salguero-Gomez

Stanford University (Tulja lab)

Oxford University (Rob Salguer0-Gomez lab)



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RECONCILING RESILIENCE ACROSS
 ECOLOGICAL SYSTEMS, SPECIES AND SUBDISCIPLINES
 Essay Review



Unifying the concepts of stability and resilience in ecology

Koenraad Van Meerbeek^{1,2,3} | Tommaso Jucker⁴ | Jens-Christian Svenning^{2,3}

PRESS vs. PULSE ?

Simplest thing:

A PRESS

IS JUST

A CONTINUED SERIES OF PULSES

Structured Population Model (LINEAR!)

$$n(t + 1) = B n(t)$$

Discrete time t
Population vector $n(t)$
Non-negative Matrix B

u **S**(table) **S**(tage) **D**(istribution)

λ_0 Long-run Growth Rate = Dominant Eigenvalue

v **S**(table) **R**(eproductive) **V**(alue)

$$B u = \lambda_0 u$$

$$v^T B = \lambda_0 v^T$$

NON-STABLE STAGE
DISTRIBUTION

$$\hat{u} \rightarrow u$$

SSD AS TIME GOES
BY

$$Q_0 = u v^T$$

STABLE PART

UNSTABLE PART

$$Q_1 = \left(\frac{B}{\lambda_0} - Q_0 \right)$$

$$\left(\frac{B}{\lambda_0} \right) = Q_0 + Q_1$$

ADD!

ANY NON-STABLE STAGE
DISTRIBUTION CAN BE
DECOMPOSED

Stable Bit

UNStable Bit

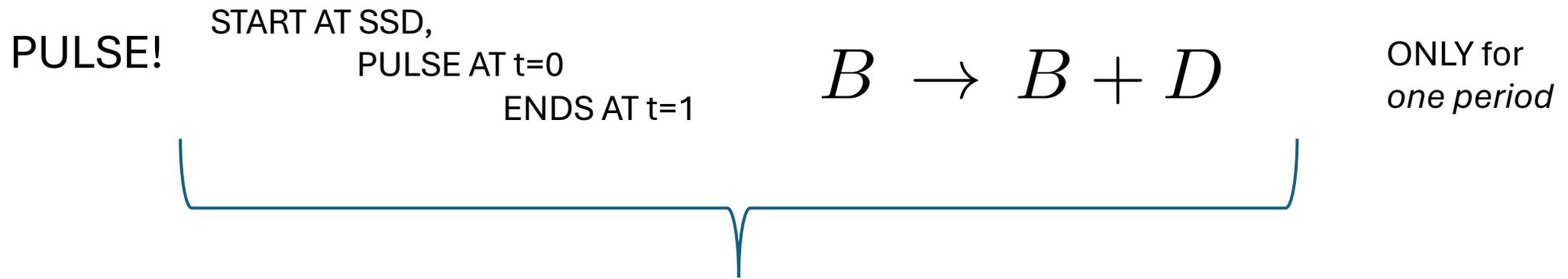
$$\hat{u} = k u + u_{\perp},$$

$$Q_0 u_{\perp} = [u v^T] u_{\perp} = 0 \leftarrow \text{Perpendicular}$$

$$\left(\frac{B^t}{\lambda_0^t} \right) \hat{u} = k u + Q_1^t u_{\perp}$$

POPULATION DYNAMICS

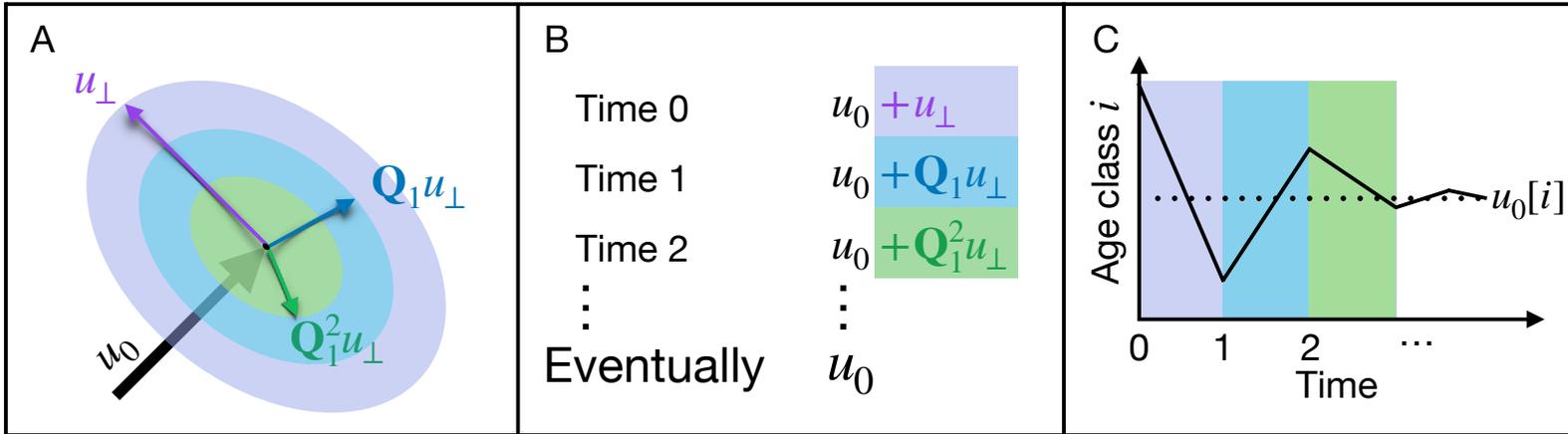
TRANSIENT PART



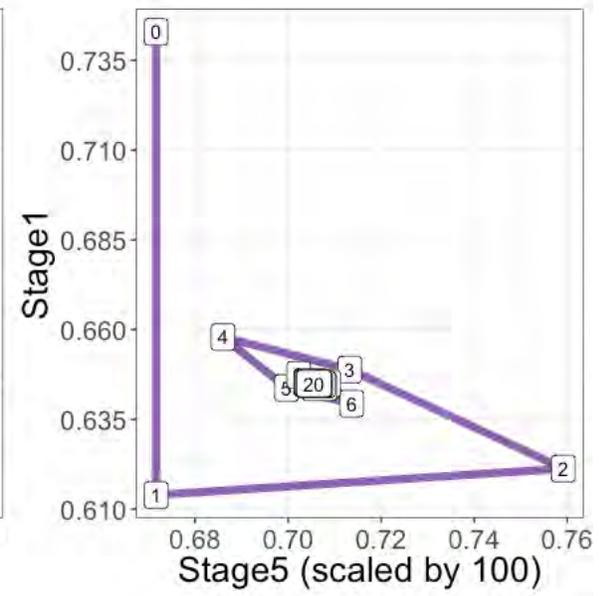
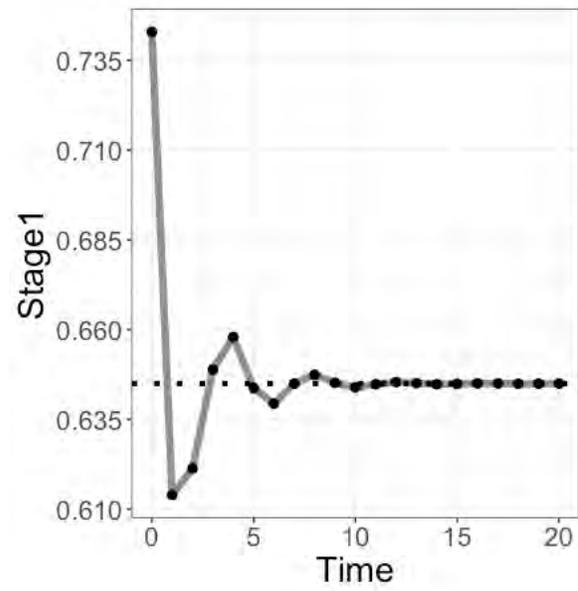
start with NOT-STABLE POPULATION AT t=1

$$u(1) = k u + u_{\perp}$$

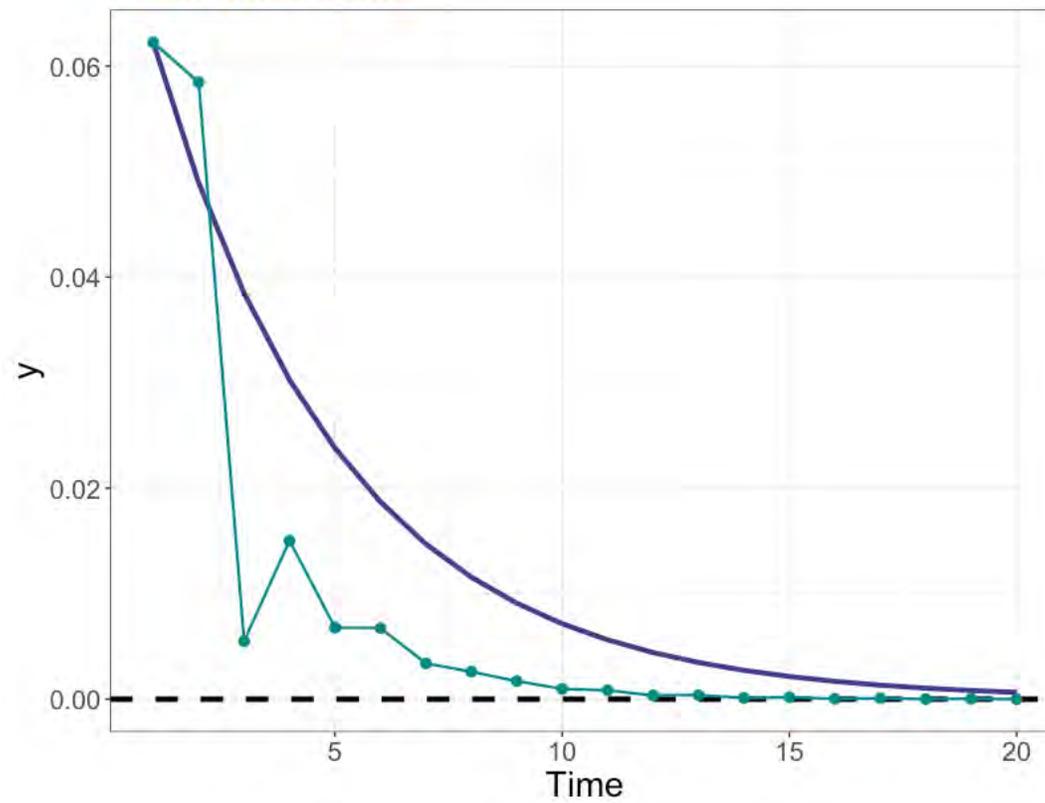
$$u(t + 1) = k u + Q_1^t u_{\perp}$$



Pulse Disturbance



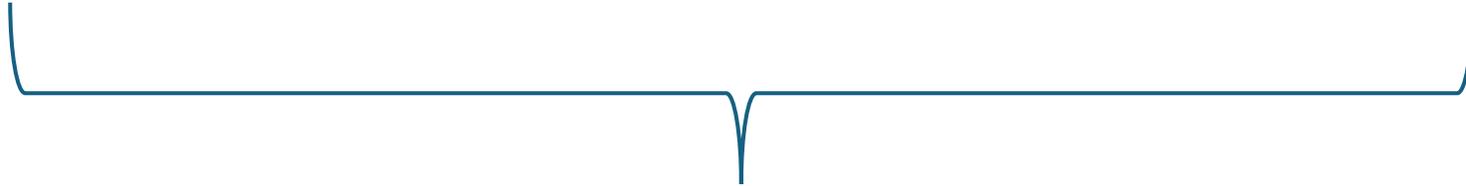
Pulse Disturbance



PRESS!
START AT SSD,
PULSE AT $t=0, 1, 2, \dots$
DOES NOT END

$$B \rightarrow B + \epsilon D$$

for
ever



Known: long-run growth rate changes to

$$\mu = \lambda_0 + \epsilon (v^T D u)$$

Start with SSD at $t=0$

$$N(0) = u$$

A pulse at time $t=0$

$$\frac{N(1)}{\mu} = u + z^*$$

The added bit is
PERPENDICULAR

$$z^* = (I - Q_0) \frac{D}{\lambda_0} u$$

Another pulse at
time $t=1$

$$\frac{n(2)}{\mu^2} = u + z^* + Q_1 z^*$$

and so on ...

Yet another pulse
at time $t-1$

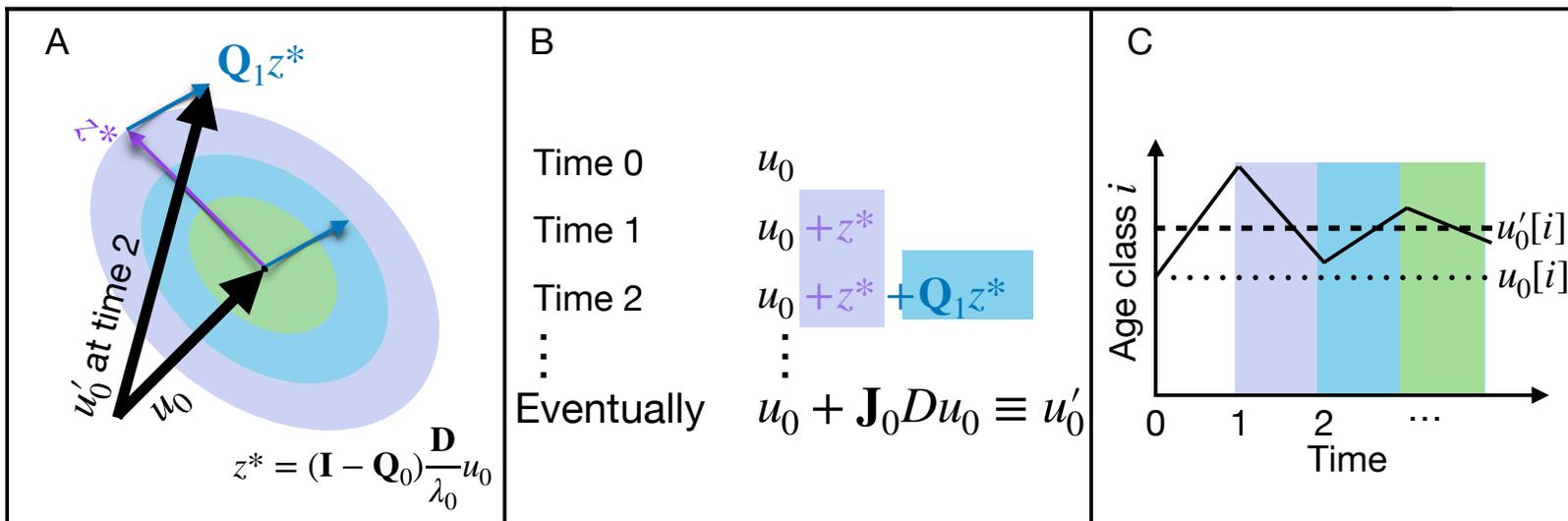
$$\frac{n(t)}{\mu^t} = u + z^* + Q_1 z^* + \dots + Q_1^{t-1} z^*$$

EFFECT OF PRESS =
CUMULATIVE EFFECT
OF REPEATED PULSES

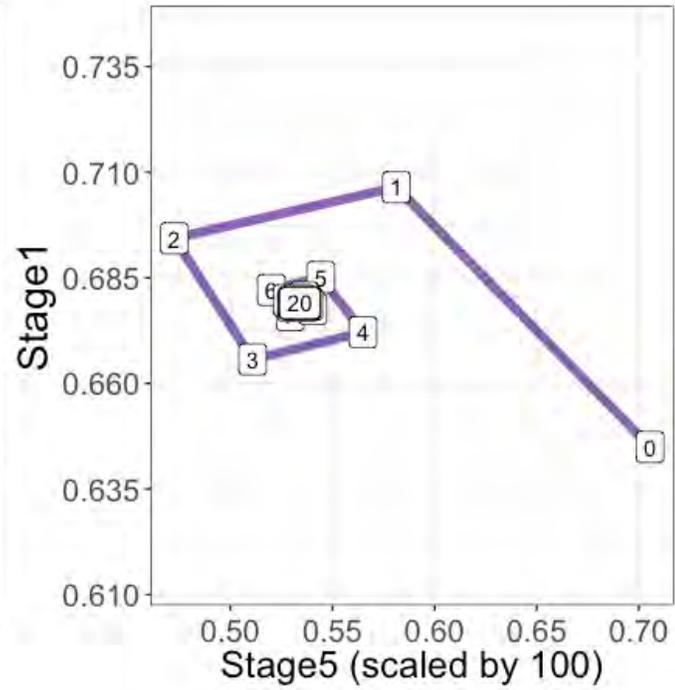
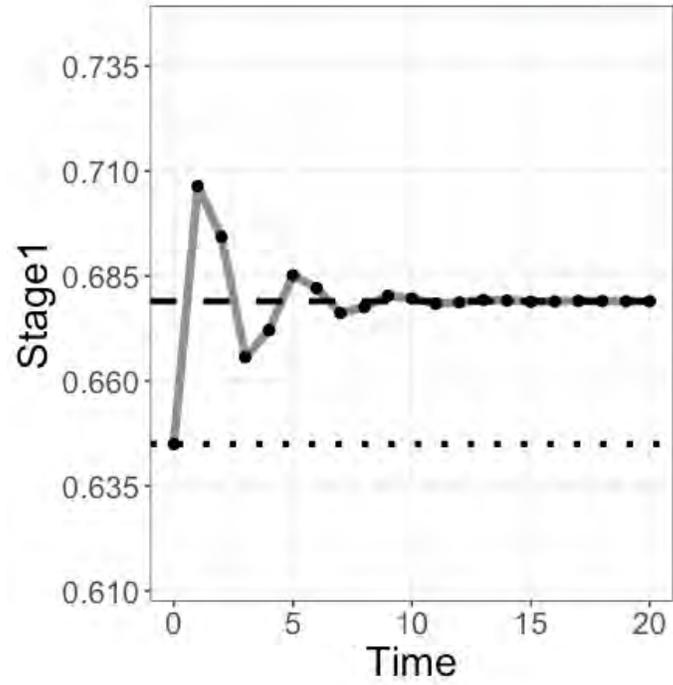
$$J_0 = \frac{1}{\lambda_0} (I - Q_1)^{-1} (I - Q_0)$$

EFFECT OF PRESS:
FINAL POPULATION
STRUCTURE

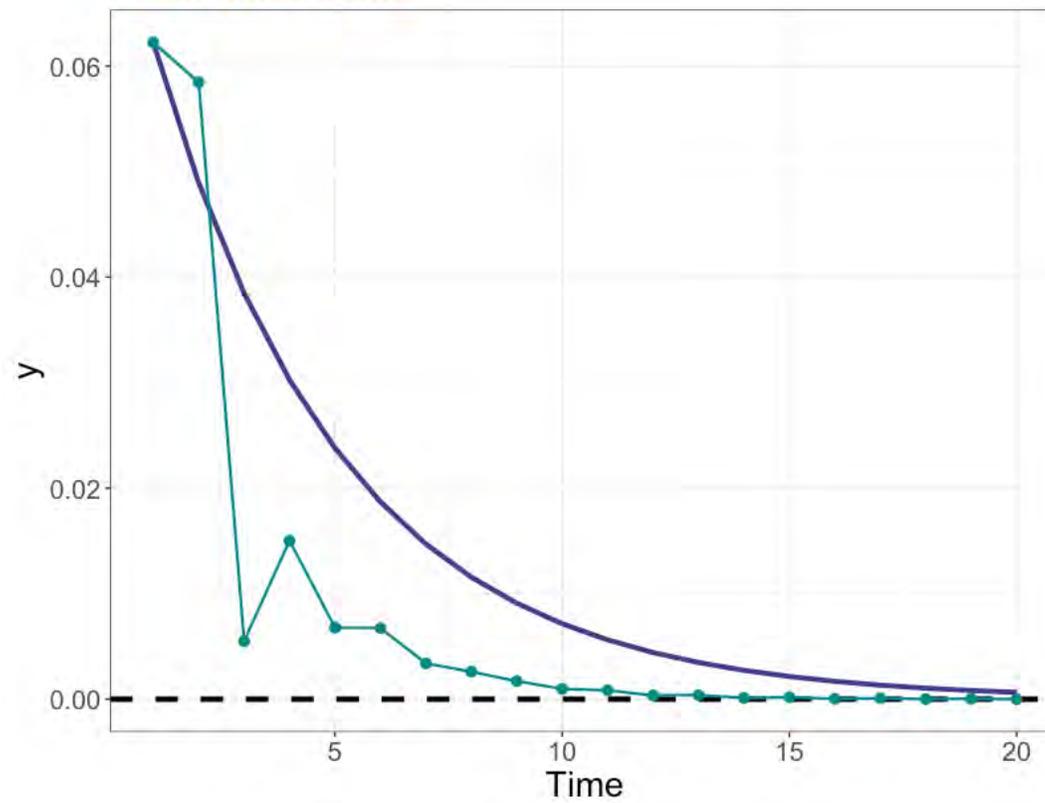
$$u + J_0 D u$$



Press Disturbance



Pulse Disturbance



DENSITY-DEPENDENT MODELS WITH ONE EQUILIBRIUM: **ONE** OR **MANY** SPECIES

MODEL

$$n(t + 1) = A(\theta, n) n(t)$$

EQUILIBRIUM

$$A(\theta, n^*) \equiv A^*$$
$$n^* = A^* n^*$$

LOCALLY STABLE

$$n(t) = n^* + \epsilon y(t)$$
$$y(t + 1) = [A^* + \hat{C}] y(t)$$

PULSE

$$\theta \rightarrow \theta + \epsilon \phi$$

NEW
EQUILIBRIUM

$$x^* = \{I - [A + \hat{C}]\}^{-1} \tilde{C} n^*$$

Measures

$$P(t, n) = \int dm K(n|m) P(t-1, m)$$

$$P(t) = L[P(t-1)]$$

$$P^* = L[P^*]$$

P* IS LOCALLY STABLE!

